NAG Toolbox for MATLAB

f02xe

1 Purpose

f02xe returns all, or part, of the singular value decomposition of a general complex matrix.

2 Syntax

[a, b, q, sv, ph, rwork, ifail] = f02xe(a, b, wantq, wantp, 'm', m, 'n',
n, 'ncolb', ncolb)

3 Description

The m by n matrix A is factorized as

$$A = QDP^{\mathrm{H}},$$

where

$$D = \binom{S}{0}, \quad m > n,$$

$$D=S, \qquad m=n,$$

$$D = (S \quad 0), \quad m < n,$$

Q is an m by m unitary matrix, P is an n by n unitary matrix and S is a $\min(m,n)$ by $\min(m,n)$ diagonal matrix with real nonnegative diagonal elements, $sv_1, sv_2, \ldots, sv_{\min(m,n)}$, ordered such that

$$sv_1 \ge sv_2 \ge \cdots \ge sv_{\min(m,n)} \ge 0.$$

The first min(m, n) columns of Q are the left-hand singular vectors of A, the diagonal elements of S are the singular values of A and the first min(m, n) columns of P are the right-hand singular vectors of A.

Either or both of the left-hand and right-hand singular vectors of A may be requested and the matrix C given by

$$C = O^{\mathrm{H}}B$$
.

where B is an m by ncolb given matrix, may also be requested.

The function obtains the singular value decomposition by first reducing A to upper triangular form by means of Householder transformations, from the left when $m \ge n$ and from the right when m < n. The upper triangular form is then reduced to bidiagonal form by Givens plane rotations and finally the QR algorithm is used to obtain the singular value decomposition of the bidiagonal form.

Good background descriptions to the singular value decomposition are given in Dongarra *et al.* 1979, Hammarling 1985 and Wilkinson 1978. Note that this function is not based on the LINPACK function CSVDC/ZSVDC.

Note that if K is any unitary diagonal matrix so that

$$KK^{\mathrm{H}} = I$$
,

then

$$A = (QK)D(PK)^{H}$$

is also a singular value decomposition of A.

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4 References

Dongarra J J, Moler C B, Bunch J R and Stewart G W 1979 *LINPACK Users' Guide* SIAM, Philadelphia Hammarling S 1985 The singular value decomposition in multivariate statistics *SIGNUM Newsl.* **20 (3)** 2–25

Wilkinson J H 1978 Singular Value Decomposition – Basic Aspects Numerical Software – Needs and Availability (ed D A H Jacobs) Academic Press

5 Parameters

5.1 Compulsory Input Parameters

1: a(lda,*) - complex array

The first dimension of the array **a** must be at least $max(1, \mathbf{m})$

The second dimension of the array must be at least $max(1, \mathbf{n})$

The leading m by n part of the array \mathbf{a} must contain the matrix A whose singular value decomposition is required.

2: b(ldb,*) – complex array

The first dimension, ldb, of the array b must satisfy

```
if ncolb > 0, ldb \ge max(1, m); ldb \ge 1 otherwise.
```

The second dimension of the array must be at least max(1, ncolb)

If ncolb > 0, the leading m by ncolb part of the array b must contain the matrix to be transformed.

3: wantq – logical scalar

Must be true if the left-hand singular vectors are required.

If wantq = false, the array q is not referenced.

4: wantp – logical scalar

Must be true if the right-hand singular vectors are required.

If wantp = false, the array ph is not referenced.

5.2 Optional Input Parameters

1: m - int32 scalar

2:

m, the number of rows of the matrix A.

Constraint: $\mathbf{m} \geq 0$.

If $\mathbf{m} = 0$, an immediate return is effected

n – int32 scalar

Default: The second dimension of the array **a**.

n, the number of columns of the matrix A.

Constraint: $\mathbf{n} \geq 0$.

If $\mathbf{n} = 0$, an immediate return is effected

3: ncolb - int32 scalar

Default: The second dimension of the array b.

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ncolb, the number of columns of the matrix B.

If $\mathbf{ncolb} = 0$, the array **b** is not referenced.

Constraint: $\mathbf{ncolb} \geq 0$.

5.3 Input Parameters Omitted from the MATLAB Interface

lda, ldb, ldq, ldph, cwork

5.4 Output Parameters

1: a(lda,*) - complex array

The first dimension of the array **a** must be at least $max(1, \mathbf{m})$

The second dimension of the array must be at least $max(1, \mathbf{n})$

If $m \ge n$ and wantq = true, the leading m by n part of a will contain the first n columns of the unitary matrix Q.

If $\mathbf{m} < \mathbf{n}$ and $\mathbf{wantp} = \mathbf{true}$, the leading m by n part of a will contain the first m rows of the unitary matrix P^{H} .

If $m \ge n$ and wantq = false and wantp = true, the leading n by n part of a will contain the first n rows of the unitary matrix P^H .

Otherwise the leading m by n part of \mathbf{a} is used as internal workspace.

2: b(ldb,*) – complex array

The first dimension, ldb, of the array b must satisfy

```
if ncolb > 0, ldb \ge max(1, m); ldb > 1 otherwise.
```

The second dimension of the array must be at least max(1, ncolb)

Contains the m by ncolb matrix $Q^{H}\mathbf{b}$.

3: q(ldq,*) - complex array

The first dimension, **ldq**, of the array **q** must satisfy

```
if m < n and wantq = true, ldq \ge max(1, m); ldq \ge 1 otherwise.
```

The second dimension of the array must be at least $max(1, \mathbf{m})$ if $\mathbf{m} < \mathbf{n}$ and $\mathbf{wantq} = \mathbf{true}$,, and at least 1 otherwise

If $\mathbf{m} < \mathbf{n}$ and $\mathbf{wantq} = \mathbf{true}$, the leading m by m part of the array \mathbf{q} will contain the unitary matrix Q. Otherwise the array \mathbf{q} is not referenced.

4: sv(*) – double array

Note: the dimension of the array sv must be at least min(m, n).

The min(m, n) diagonal elements of the matrix S.

5: **ph(ldph,*) - complex array**

The first dimension, ldph, of the array ph must satisfy

```
if m \ge n and wantq = true and wantp = true, ldph \ge max(1, n); ldph \ge 1 otherwise.
```

The second dimension of the array must be at least $max(1, \mathbf{n})$ if $\mathbf{m} \ge \mathbf{n}$ and $\mathbf{wantq} = \mathbf{true}$ and $\mathbf{wantp} = \mathbf{true}$, and at least 1 otherwise

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If $m \ge n$ and wantq and wantp are true, the leading n by n part of the array ph will contain the unitary matrix P^{H} . Otherwise the array ph is not referenced.

6: rwork(*) – double array

Note: the dimension of the array **rwork** must be at least max(1, lrwork), where lrwork must satisfy:

 $lrwork = 2 \times (min(\mathbf{m}, \mathbf{n}) - 1)$, when ncolb = 0 and wantq and wantp are false,

 $lrwork = 3 \times (min(\mathbf{m}, \mathbf{n}) - 1)$, when either ncolb = 0 and wantq = false and wantp = true, or wantp = false and one or both of ncolb > 0 and wantq = true,

$$lrwork = 5 \times (min(\mathbf{m}, \mathbf{n}) - 1)$$
, otherwise.

 $\mathbf{rwork}(\min(\mathbf{m}, \mathbf{n}))$ contains the total number of iterations taken by the *QR* algorithm.

The rest of the array is used as workspace.

7: ifail – int32 scalar

0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail
$$= -1$$

One or more of the following conditions hold:

```
\begin{array}{l} \textbf{m}<0;\\ \textbf{n}<0;\\ \textbf{lda}<\textbf{m};\\ \textbf{ncolb}<0;\\ \textbf{ldb}<\textbf{m} \text{ and } \textbf{ncolb}>0;\\ \textbf{ldq}<\textbf{m} \text{ and } \textbf{m}<\textbf{n} \text{ and } \textbf{wantq}=\textbf{true};\\ \textbf{ldph}<\textbf{n} \text{ and } \textbf{m}\geq\textbf{n} \text{ and } \textbf{wantq}=\textbf{true} \text{ and } \textbf{wantp}=\textbf{true}. \end{array}
```

ifail > 0

The QR algorithm has failed to converge in $50 \times \min(m,n)$ iterations. In this case $\mathbf{sv}(1), \mathbf{sv}(2), \dots, \mathbf{sv}(\mathbf{ifail})$ may not have been found correctly and the remaining singular values may not be the smallest. The matrix A will nevertheless have been factorized as $A = QEP^H$ where the leading $\min(m,n)$ by $\min(m,n)$ part of E is a bidiagonal matrix with $\mathbf{sv}(1), \mathbf{sv}(2), \dots, \mathbf{sv}(\min(m,n))$ as the diagonal elements and $\mathbf{rwork}(1), \mathbf{rwork}(2), \dots, \mathbf{rwork}(\min(m,n)-1)$ as the superdiagonal elements.

This failure is not likely to occur.

7 Accuracy

The computed factors Q, D and P satisfy the relation

$$QDP^{H} = A + E,$$

where

$$||E|| \leq c\epsilon ||A||$$
,

 ϵ is the *machine precision*, c is a modest function of m and n and $\|.\|$ denotes the spectral (two) norm. Note that $\|A\| = sv_1$.

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8 Further Comments

>Following the use of f02xe the rank of A may be estimated as follows:

```
tol = eps;
irank = 1;
while (irank <= numel(sv) && sv(irank) >= tol*sv(1) )
  irank = irank + 1;
end
```

returns the value k in irank, where k is the smallest integer for which $\mathbf{sv}(k) < tol \times \mathbf{sv}(1)$, where tol is typically the machine precision, so that irank is an estimate of the rank of S and thus also of A.

9 Example

```
a = [complex(0, +0), complex(-0.5, +1.5), complex(-1, +1);
     complex(0, +0), complex(0.9, +1.3), complex(0.2, +1.4); complex(0, +0), complex(-0.4, +0.4), complex(1.8, +0);
     complex(0, +0), complex(0.1, +0.7), complex(0, +0);
     complex(0, -0.3), complex(0.3, +0.3), complex(0, +2.4)];
b = [complex(-0.55, +1.05); complex(0.49, 0.93); complex(0.56, -0.16);
complex(0.39, 0.23); complex(1.13,0.83)];
wantq = true;
wantp = true;
[aOut, bOut, q, sv, ph, rwork, ifail] = f02xe(a, b, wantq, wantp)
aOut =
  0.3644 - 0.3465i
                    0.2375 - 0.3371i -0.1873 + 0.1216i
  -0.0585 - 0.4994i -0.1272 - 0.3923i -0.0151 + 0.2228i
  0.0270 - 0.0745i
0 - 0.6017i
                    0.0482 - 0.3211i 0.0017 - 0.1000i
0 + 0.3613i 0 - 0.7124i
                          0 + 0.3613i
bOut =
  -1.7569 + 1.1703i
  -0.2878 - 0.1256i
   0.1727 + 0.5342i
  0.3608 + 0.0110i
  0.0548 + 0.1295i
  5.0215e-236 - 1.7942e-54i
sv =
    3.9002
    1.9577
   0.2143
ph =
                    -0.3856 + 0.2052i -0.8981 + 0.0225i
  0.0463
  -0.0554
                    -0.8613 + 0.2578i 0.4277 + 0.0754i
                    0.9974
rwork =
   -0.0000
   -0.0000
   6.0000
    3.2500
    3.2500
   -0.0000
   0.9826
   1.0000
   -0.1858
   -0.0000
ifail =
           0
```

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